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# SD 500

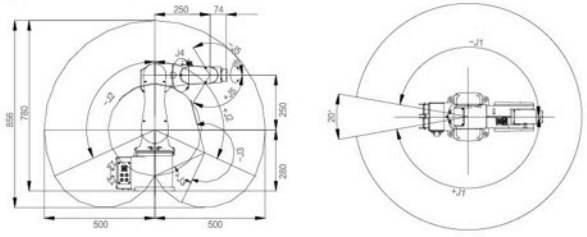
## Product Introduction

SD Series robots are compact, small and lightweight, ideal for material handling, picking up and sorting, and assembly applications with fast speed and high accuracy. With build-in cables, SD Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Material handling
- Assembly

## Working Space




## Technical Specifications

| Model | | SD 500 |
|---|---|---|
| Wrist Payload | | 1kg(Rated) |
| | | 3kg(Max.) |
| Max Working Radius | | 500 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 375° /s |
| | J2 | 375° /s |
| | J3 | 430° /s |
| | J4 | 460° /s |
| | J5 | 460° /s |
| | J6 | 600° /s |
| Max Operation Area | J1 | ±170° |
| | J2 | ±115° |
| | J3 | +40°~-220° |
| | J4 | ±185° |
| | J5 | ±125° |
| | J6 | ±360° |
| The Max Moment Allowable Torque | J5 | 35 Nm |
| | J6 | 24 Nm |
| Weight | | 26 kg |
| Position Repeatability | | ±0.015 mm |
| Working Temperature | | 0~45℃ |


# SD 700

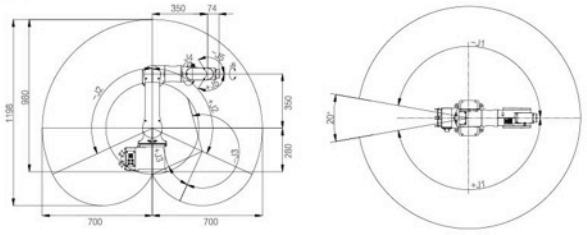
## Product Introduction

SD Series robots are compact, small and lightweight, ideal for material handling, picking up and sorting, and assembly applications with fast speed and high accuracy. With build-in cables, SD Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Material handling
- Assembly

## Working Space




## Technical Specifications

| Model | | SD 700 |
|---|---|---|
| Wrist Payload | | 1kg(Rated) |
| | | 3kg(Max.) |
| Max Working Radius | | 700 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 250° /s |
| | J2 | 185° /s |
| | J3 | 290° /s |
| | J4 | 460° /s |
| | J5 | 460° /s |
| | J6 | 600° /s |
| Max Operation Area | J1 | ±170° |
| | J2 | ±115° |
| | J3 | +40°~-220° |
| | J4 | ±185° |
| | J5 | ±125° |
| | J6 | ±360° |
| The Max Moment Allowable Torque | J5 | 35 Nm |
| | J6 | 24 Nm |
| Weight | | 28 kg |
| Position Repeatability | | ±0.02 mm |
| Working Temperature | | 0~45℃ |

# SA 1400

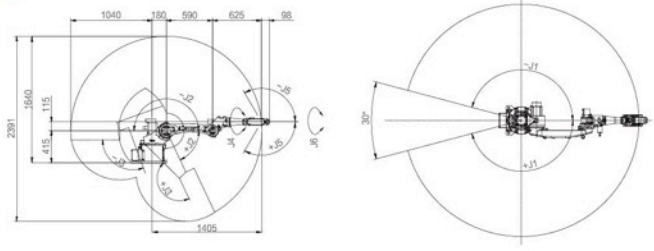
## Product Introduction

SA Series robots are compact, small and lightweight, ideal for welding application due to its high stability. It can realize high welding-path accuracy, considerably reduce welding cycle-time, and extend the lifetime of tubes and cables. In addition, SA Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Arc welding
- Material handling
- Cutting
- Palletizing

## Working Space




## Technical Specifications

| Model | | SA 1400 |
|---|---|---|
| Wrist Payload | | 6 kg |
| Max Working Radius | | 1405 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 150° /s |
| | J3 | 160° /s |
| | J4 | 360° /s |
| | J5 | 320° /s |
| | J6 | 360° /s |
| Max Operation Area | J1 | ± 150° |
| | J2 | +65° ~ −180° |
| | J3 | +160° ~ −110° |
| | J4 | ± 170° |
| | J5 | ± 120° |
| | J6 | ± 360° |
| The Max Moment Allowable Torque | J5 | 54 Nm |
| | J6 | 23 Nm |
| Weight | | 140 kg |
| Position Repeatability | | ± 0.05 mm |
| Working Temperature | | 0 ~ 45℃ |


# SA 1500

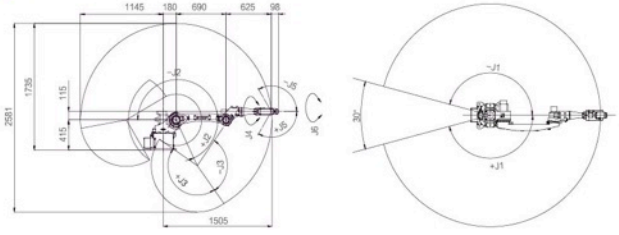
## Product Introduction

SA Series robots are compact, small and lightweight, ideal for welding application due to its high stability. It can realize high welding-path accuracy, considerably reduce welding cycle-time, and extend the lifetime of tubes and cables. In addition, SA Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Arc welding
- Material handling
- Cutting
- Palletizing

## Working Space




## Technical Specifications

| Model | | SA 1500 |
|---|---|---|
| Wrist Payload | | 6 kg |
| Max Working Radius | | 1505 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 150° /s |
| | J3 | 160° /s |
| | J4 | 360° /s |
| | J5 | 320° /s |
| | J6 | 360° /s |
| Max Operation Area | J1 | ± 150° |
| | J2 | +65° ~ −180° |
| | J3 | +160° ~ −110° |
| | J4 | ± 170° |
| | J5 | ± 120° |
| | J6 | ± 360° |
| The Max Moment Allowable Torque | J5 | 54 Nm |
| | J6 | 23 Nm |
| Weight | | 145 kg |
| Position Repeatability | | ± 0.05 mm |
| Working Temperature | | 0 ~ 45℃ |

# SA 1800

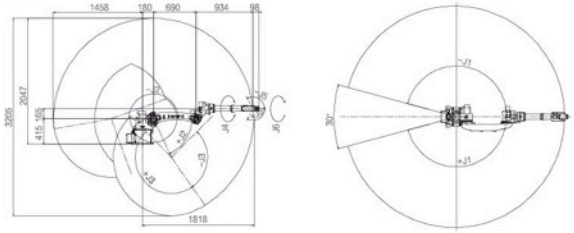
## Product Introduction

SA Series robots are compact, small and lightweight, ideal for welding application due to its high stability. It can realize high welding-path accuracy, considerably reduce welding cycle-time, and extend the lifetime of tubes and cables. In addition, SA Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Arc welding
- Material handling
- Cutting
- Palletizing

## Working Space




## Technical Specifications

| Model | | SA 1800 |
|---|---|---|
| Wrist Payload | | 8 kg |
| Max Working Radius | | 1818 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 150° /s |
| | J3 | 160° /s |
| | J4 | 360° /s |
| | J5 | 320° /s |
| | J6 | 360° /s |
| Max Operation Area | J1 | ±165° |
| | J2 | +65° ~−180° |
| | J3 | +170° ~−100° |
| | J4 | ±185° |
| | J5 | ±120° |
| | J6 | ±360° |
| The Max Moment Allowable Torque | J5 | 54 Nm |
| | J6 | 29 Nm |
| Weight | | 148 kg |
| Position Repeatability | | ±0.05 mm |
| Working Temperature | | 0~45℃ |


# SA 2010

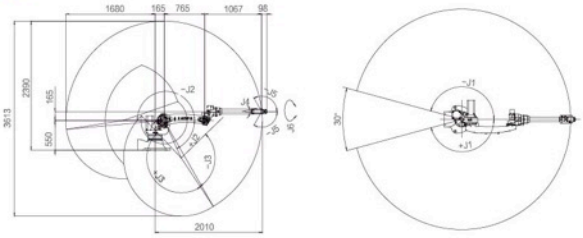
## Product Introduction

SA Series robots are compact, small and lightweight, ideal for welding application due to its high stability. It can acquire high welding-path accuracy, considerably reduce welding cycle-time, and extend the lifetime of tubes and cables. In addition, SA Series robots can fit in narrow working space and can be floor mounted, inverted or tilted in any angle.

## Main Applications

- Arc welding
- Material handling
- Cutting
- Palletizing

## Working Space




## Technical Specifications

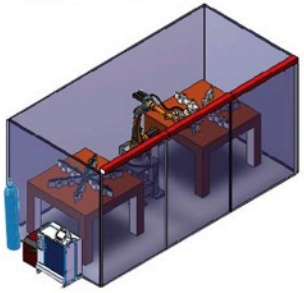
| Model | | SA 2010 |
|---|---|---|
| Wrist Payload | | 8 kg |
| Max Working Radius | | 2010 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 120° /s |
| | J3 | 120° /s |
| | J4 | 360° /s |
| | J5 | 320° /s |
| | J6 | 360° /s |
| Max Operation Area | J1 | ±165° |
| | J2 | +65° ~−180° |
| | J3 | +170° ~−100° |
| | J4 | ±185° |
| | J5 | ±120° |
| | J6 | ±360° |
| Weight | | 232 kg |
| Position Repeatability | | ±0.05 mm |
| Working Temperature | | 0~45℃ |

# SA Robots welding solutions

## SA1800 welding system

### 1.System description

One SA1800 deals with two welding work stations while manual worker is responsible for material handling. After accurately locate the workpiece by positioner and pneumatic gripper SA1800 starts welding.



### 2.Technological process

1)SA1800 deals with two workstation on its left and right sides.

2)Automatic door on the left side is closed and the right side one stays open for material handling by manual worker when SA1800 is welding on the left work station, vice versa.

3)In order to plan the welding sequences within welding area, it is important to take into consideration of how to manage the extent of welding deformation (e.g. symmetry welding can greatly decrease deformation), and trying to decrease robot's walking time and the time for changing positions.

### 3.System characteristics

1)Safe and stable;

2) Firmly welding, perfect welding seam, high stability;

3) Clamping workpieces accurately and conveniently.

4) Able to clamp workpieces with similar specifications and sizes and clamper is easy and convenient to adjust.

### 4. Main configuration

| | Device | Function description | Quantity |
|---|---|---|---|
| 1 | Robot SA1800 | Welding Robot | 1 Piece |
| 2 | Clamper Station | Placing and locating workpieces | 2 Sets |
| 3 | Wire-feeder, welding machine and accessories | Managing wire-feeder, welding data, power source and accessories | 1 set |
| 4 | Welding Torch | For welding | 1 piece for each working station |
| 5 | Button case, Indicator light | Buttons of 'start', 'stop', 'emergency stop', and 'start welding' etc. | 1 set |
| 6 | Shadow shield (with protection function) | Shielding, protection | 1 set |
| 7 | Automatic safety door | Shielding, protection | 2 sets |

# SP200

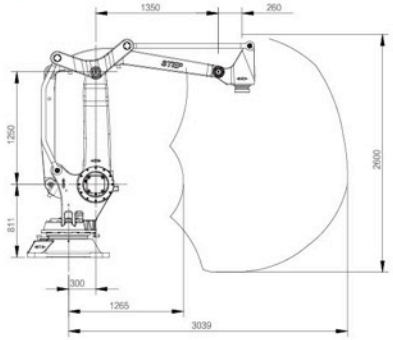
## Product Introduction

SP Series robots are 4-axis robots with simple structure, low failure rate. This model has many advantages such as easy to operate, saving energy, with less area occupation etc. Large payload capability enables the robot to handle materials easily which is suitable for heavy loading and large-scale working environment.

## Main Applications

- Handling
- Palletizing

## Working Space




## Technical Specifications

| Model | | SP200 |
|---|---|---|
| Wrist Payload | | 200 kg |
| Max Working Radius | | 3039 mm |
| Number of axis | | 4 |
| Max Speed | J1 | 120° /s |
| | J2 | 120° /s |
| | J3 | 120° /s |
| | J4 | 300° /s |
| Max Operation Area | J1 | ± 180° |
| | J2 | +75° ~ −40° |
| | J3 | +115° ~ −20° |
| | J4 | ± 360° |
| Weight | | 1815 kg |
| Position Repeatability | | ± 0.5 mm |
| Working Temperature | | 0 ~ 45℃ |

# SP275

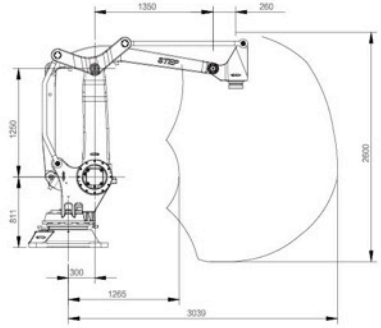
## Product Introduction

SP Series robots are 4-axis robots with simple structure, low failure rate. This model has many advantages such as easy to operate, saving energy, with less area occupation etc. Large payload capability enables the robot to handle materials easily which is suitable for heavy loading and large-scale working environment.

## Main Applications

- Handling
- Palletizing

## Working Space




## Technical Specifications

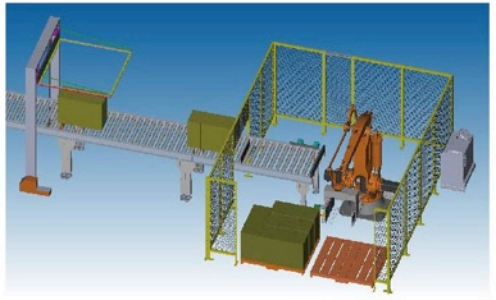
| Model | | SP275 |
|---|---|---|
| Wrist Payload | | 275 kg |
| Max Working Radius | | 3039 mm |
| Number of axis | | 4 |
| Max Speed | J1 | 80° /s |
| | J2 | 80° /s |
| | J3 | 80° /s |
| | J4 | 200° /s |
| Max Operation Area | J1 | ±180° |
| | J2 | +75° ~−40° |
| | J3 | +115° ~−20° |
| | J4 | ±360° |
| Weight | | 1850 kg |
| Position Repeatability | | ±0.5 mm |
| Working Temperature | | 0~45℃ |


# SP Robots solutions

## SP200 palletizing system

### 1.System description

One SP200 works on air-conditioner palletizing. Air-conditioners are feed into packaging area through the roller conveyor then to be send to the end for palletizing.



### 2.Technological process

1)Automatic packaging machine packs the workpieces transported by roller conveyor;

2)Robot sit at the end of roller conveyor grips the workpiece rapidly;

3)Robot stacks the workpieces based on the set pattern required by clients;

4)After one stack, SP200 starts to palletize another one.

### 3.System characteristics

1)Safe and stable;

2) By using 4-axis palletizing robot to shorten the cycle-time;

3) The precision can be secured by using the gripper with high accuracy and high stability.

4) Able to grip workpieces with similar specifications and sizes and gripper is easy and convenient to adjust.

### 4. Main configuration

| | Device | Purpose | Quantity |
|---|---|---|---|
| 1 | SP200 robot | For palletizing | 1 Piece |
| 2 | Gripper | For gripping air-conditioner | 1 set |
| 3 | Stacked plate | For placing air-conditioner | 2 Sets |
| 4 | Roller conveyor and positioner | For positioning air-conditioner | 1 set |
| 5 | Security fence and other devices | | 1 set |

## SR20

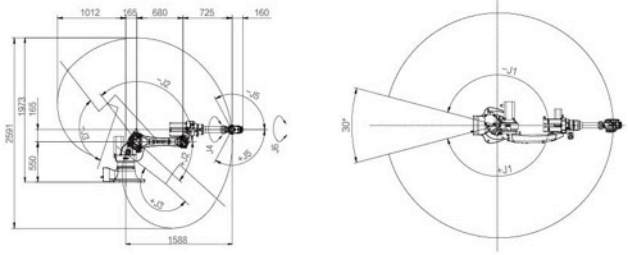
### Product Introduction

With compact structure, SR series robots are equipped with high-precision reducer, allowing the rotating arm can work flexibly within limited space with high speed, suitable for handling, palletizing, assembly etc. In addition, SR robots can be mounted flexibly.

### Main Applications

- Material handling
- Assembly
- Palletizing

### Working Space




### Technical Specifications

| Model | | SR20 |
|---|---|---|
| Wrist Payload | | 20 kg |
| Max Working Radius | | 1588 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 120° /s |
| | J3 | 120° /s |
| | J4 | 360° /s |
| | J5 | 300° /s |
| | J6 | 450° /s |
| Max Operation Area | J1 | ± 165° |
| | J2 | +40° ~ −155° |
| | J3 | +165° ~ −100° |
| | J4 | ± 360° |
| | J5 | ± 120° |
| | J6 | ± 360° |
| The Max Moment Allowable Torque | J5 | 186 Nm |
| | J6 | 98 Nm |
| Weight | | 240 kg |
| Position Repeatability | | ± 0.05 mm |
| Working Temperature | | 0 ~ 45℃ |


## SR25

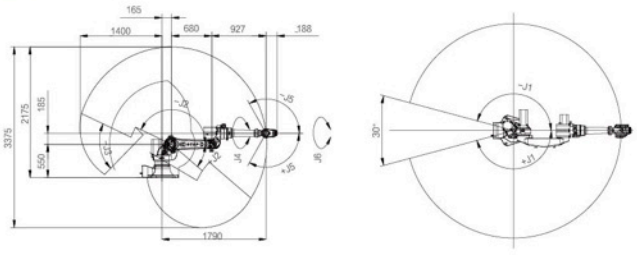
### Product Introduction

SR Series welding dedicated robots are compact, small and lightweight, ideal for welding application due to its high stability. It can acquire high welding-path accuracy, considerably reduce welding cycle-time, and extend the lifetime of tubes and cables. In addition, SR Series robots can fit in narrow working space and can be floor mounted, inverted or on the wall in any angle.

### Main Applications

- Arc welding
- Palletizing
- Material handling

### Working Space




### Technical Specifications

| Model | | SR25 |
|---|---|---|
| Wrist Payload | | 25 kg |
| Max Working Radius | | 1790 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 150° /s |
| | J2 | 120° /s |
| | J3 | 120° /s |
| | J4 | 300° /s |
| | J5 | 300° /s |
| | J6 | 360° /s |
| Max Operation Area | J1 | ± 165° |
| | J2 | +40° ~ −155° |
| | J3 | +170° ~ −70° |
| | J4 | ± 360° |
| | J5 | ± 120° |
| | J6 | ± 360° |
| The Max Moment Allowable Torque | J5 | 382 Nm |
| | J6 | 255 Nm |
| Weight | | 288 kg |
| Position Repeatability | | ± 0.05 mm |
| Working Temperature | | 0 ~ 45℃ |

## SR50

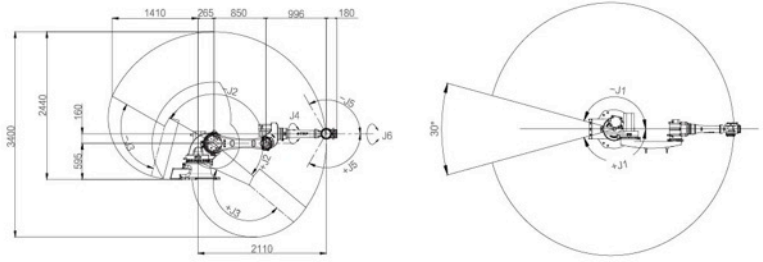
### Product Introduction

With compact structure, SR series robots are equipped with high-precision reducer, allowing the rotating arm can work flexibly within limited space with high speed, suitable for handling, palletizing, assembly etc. In addition, SR robots can be mounted flexibly.

### Main Applications

- Material handling
- Casting
- Welding
- Deburring
- Palletizing
- Assembly
- Polishing

### Working Space




### Technical Specifications

| Model | | SR50 |
|---|---|---|
| Wrist Payload | | 50 kg |
| Max Working Radius | | 2110 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 120° /s |
| | J2 | 100° /s |
| | J3 | 100° /s |
| | J4 | 180° /s |
| | J5 | 180° /s |
| | J6 | 200° /s |
| Max Operation Area | J1 | ±165° |
| | J2 | +40° ~−150° |
| | J3 | +165° ~−105° |
| | J4 | ±360° |
| | J5 | ±120° |
| | J6 | ±360° |
| Weight | | 510 kg |
| Position Repeatability | | ±0.25 mm |
| Working Temperature | | 0~45℃ |


## SR165

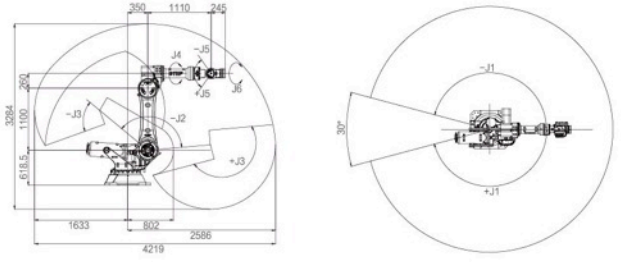
### Product Introduction

With compact structure, SR series robots are equipped with high-precision reducer, allowing the rotating arm can work flexibly within limited space with high speed, suitable for handling, palletizing, assembly etc. In addition, SR robots can be mounted flexibly.

### Main Applications

- Material handling
- Casting
- Welding
- Deburring
- Palletizing
- Assembly
- Polishing

### Working Space




### Technical Specifications

| Model | | SR165 |
|---|---|---|
| Wrist Payload | | 165 kg |
| Max Working Radius | | 2586 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 110° /s |
| | J2 | 110° /s |
| | J3 | 110° /s |
| | J4 | 175° /s |
| | J5 | 150° /s |
| | J6 | 240° /s |
| Max Operation Area | J1 | ±165° |
| | J2 | −5° ~−140° |
| | J3 | +170° ~−60° |
| | J4 | ±360° |
| | J5 | ±125° |
| | J6 | ±360° |
| Weight | | 1250 kg |
| Position Repeatability | | ±0.25 mm |
| Working Temperature | | 0~45℃ |

# SR210

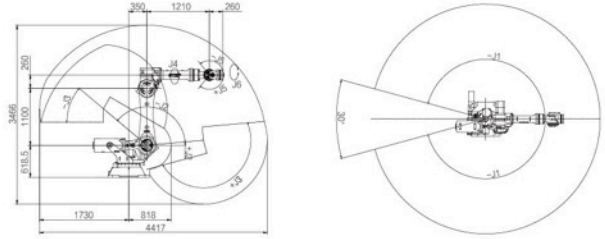
## Product Introduction

With compact structure, SR series robots are equipped with high-precision reducer, allowing the rotating arm can work flexibly within limited space with high speed, suitable for handling, palletizing, assembly etc. In addition, SR robots can be mounted flexibly.

## Main Applications

- ▲ Material handling
- ▲ Casting
- ▲ Welding
- ▲ Deburring
- ▲ Palletizing
- ▲ Assembly
- ▲ Polishing

## Working Space




## Technical Specifications

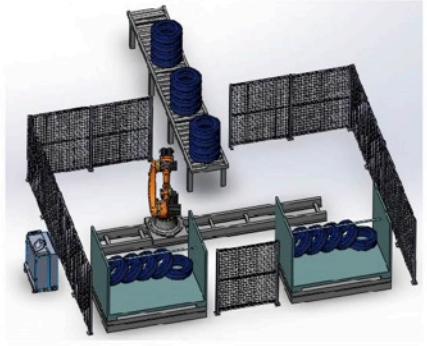
| Model | | SR210 |
|---|---|---|
| Wrist Payload | | 210 kg |
| Max Working Radius | | 2687 mm |
| Number of axis | | 6 |
| Max Speed | J1 | 95° /s |
| | J2 | 85° /s |
| | J3 | 95° /s |
| | J4 | 125° /s |
| | J5 | 125° /s |
| | J6 | 190° /s |
| Max Operation Area | J1 | ±165° |
| | J2 | −5° ~−140° |
| | J3 | +170° ~−40° |
| | J4 | ±360° |
| | J5 | ±120° |
| | J6 | ±360° |
| Weight | | 1250 kg |
| Position Repeatability | | ±0.25 mm |
| Working Temperature | | 0~45℃ |


# SR Robots solutions

## SR50 handling systems

### 1.System description

Tyre loading and unloading process are completed by SR50 on the track motion moving back and forth with high precision gripper.



### 2.Technological process

1)The end of roller conveyor positions the workpiece;
2)SR50 moves from the edge of the track close to roller conveyor to pick up the tyre;
3)By moving along the track SR50 places the tyres on rotating stacking plate;
4)Forklift truck transports the filled stack to the given area. `

### 3.System characteristics

1)Safe and stable;
2) Floor-mounted track extends the robot's working range;
3) Adopting robots gripper with high precision and high stability ensures the high accuracy to grip workpieces.
4) Able to grip workpieces with similar specifications and similar sizes.

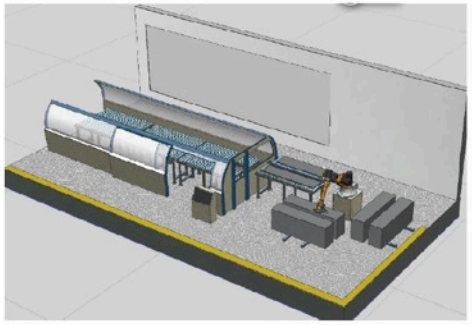
### 4. Main configuration

| | Device | Purpose | Quantity |
|---|---|---|---|
| 1 | SR50 Robot | For tyres handling | 1 piece |
| 2 | Tyre gripper | For tyres gripping | 1 set |
| 3 | Robot track | For robot moving and extending working area | 1 piece |
| 4 | Rotating stacked plate | For rotating stacked plate | 2 sets |
| 5 | Roller conveyor and positioner | For tyres transporting | 1 set |
| 6 | Security fence and other devices | | 1 set |

## SR210 Robot palletizing system

### 1.System description

This system uses SR210 to palletize the doorplate. The robot cell interacts with Salvagnini device to identify and flip workpieces.



### 2.Technological process

1)Salvagnini sends the signal to SR210 after finish bending;

2)SR210 flips the workpiece 180°.

3)SR210 moves to the unloading point to place the workpiece after received the command and then goes back to the original point.

### 3.System characteristics

1)Safe and stable;

2)Robot gripper can adjust to grip workpieces with different specifications;

3)Workpieces can be positioned accurately and rapidly.

### 4. Main configuration

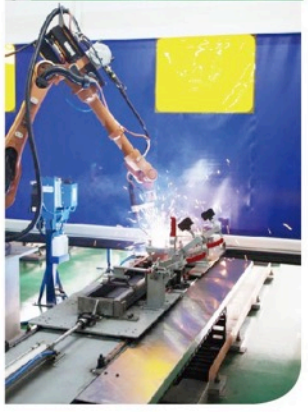
| | Device | Purpose | Quantity |
|---|---|---|---|
| 1 | SR210 Robot | For workpieces handling | 1 piece |
| 2 | Gripper | Suitable for workpieces with different sizes | 1 set |
| 3 | Turning table | For turning over the workpieces | 2 sets |
| 4 | Security fence and other devices | | 1 set |


## SRC control system

- Innovative modular design, easy for operating and maintaining, maximized availability
- Integrating robot control, security control, PLC control and motion control
- Scalable and flexible control system with outstanding performance which not only confine to be used in robots
- Real-time communication among dedicated controlling modular (Industry EtherNet)
- High compatibility with other system's software and program, which reduces the cost of upgrading and maintaining.
- Rapid and convenient operating thanks to tested instruction set for better programming by users
- Enough external interfaces function extension, meeting the demands of special industry such as welding etc.
- Higher protection level, brand-new cooling system to fit in harsher environment
- Optimizing the performance with better cost control

## System characteristics

| Specifications | | | |
|---|---|---|---|
| Electric system | Rated input voltage: 380VAC ± 10%<br>Power capacity (Max.): 20KVA(Max.)<br>Power frequency: 50Hz<br>Environment temperature: 0~40°C<br>Environment humidity: 45~80% RH | | |
| Control | Number of axis: maximum 12 axis<br>Advanced multi-processing control system<br>Advanced robot programming language<br>Portable, extendable, open<br>Pre-installed software with additional disc | | |
| Teaching pendant | 1.25kg(excluding cable)<br>6.5 inch color touch screen(VGA 640X480)<br>Emergency stop function<br>Three-position starting device<br>Supporting operation by both hands<br>Supporting USB memory<br>IP65 Protection IP65 | | |
| Maintenance | Status indicated by LED light<br>Diagnosis software and tool<br>Zero position storage function when losing power<br>Reserved remote service function | | |
| Security | Emergency stop function<br>Double channel safety circuit with monitoring function<br>Three-position starting device<br>Reserved external safety interface | | |
| Physical characteristics | Dimension (mm) | Weight | Protection available |
| Control cabinet | 650x 520 x 900 | About 150kg | IP54 |
| Extended interface | | | |
| Digital | 24VDC or electric relay signal | | |
| Analog | 0–10V | | |
| Bus communication | EtherCAT<br>CANopen<br>EtherNet/IP | | |



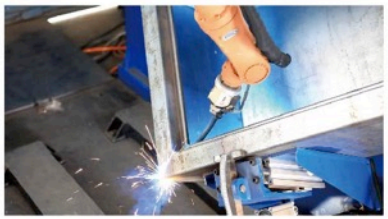
### Automatic bearing beam welding cell

Description:

SR18L8 are used for welding in this case. According to the requirements of welding technology and environment protection, positioner and walk device are adopted to make sure the separation between welding area andmanually material handling.

Results:

The number of production team of 8 workers reduced to 2, with capacity up to 50 bearing beams per day.

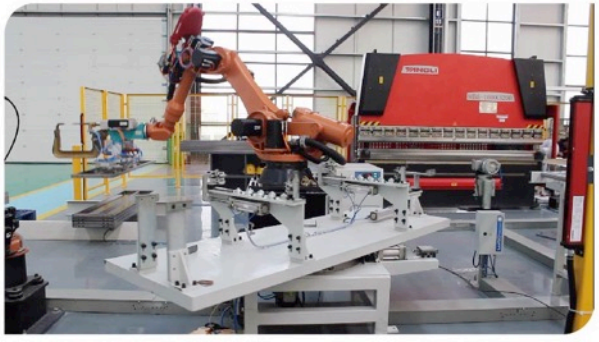
## Large safe automatic welding cell

Description:

SR18L8 was adopted in this case for welding. A dedicated welding program package was offered by R&D team to make sure the welding quality. SP275 was followed to unload the finished products.

Results:

Capacity is up to 48 boxes per day, eliminating 6 labors.



## Automatic sheet metal processing line

Description:

SR50 works together with punching machine to pierce sheet metal and cooperates with bender to bend doorplates while SR210 and SA1400 is doing spot welding and arc welding job simultaneously.

Results:

The numbers of workers reduced from 6 to 1 for taking care of robots. Un-processed sheet metal was sent in and out as the finished elevator door.

## Air-conditioner palletizing station

Description:

SP200 sits the end of air-conditioner assembly line to palletize the finished products.

Results:

2400 sets air-conditioner can be stacked per day and 3 workers' costs were saved.


## Stereoscopic warehouse

Description:

Working with visual inspection system, SR50 un-stacks and re-stacks irregular bagged materials.

Results:

Saved 5 workers/shift and capacity up to 3200 bags/8h(before 2000 bags/8h).

## Sheet metal bending

Description:

Cooperating with bender, SR50 bends the sheet metal with different specifications. STEP unique bending program package ensures that the flange strictly follows movement orbit of sheet metal for high bending precision.


## Automatic palletizing cell

Description:

SR210 (payload 210kg, reach 2700mm) works with Salvagnini sheet metal process line to unload materials.

Results:

Capacity is up to 960 sheet metals/day shift (8 hours), eliminating 4 labors.

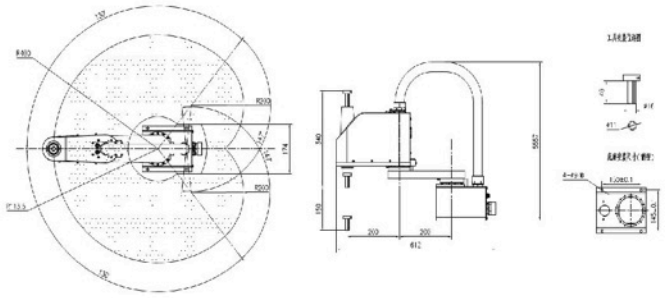
## ADT-400X4H150-011

### Product picture & Specifications


| | | | ADT-400X4H150-011 |
|---|---|---|---|
| Type | | | Horizontally multi-joint |
| Number of axis | | | 4 |
| Reach | | | 400mm |
| Axis specifications | X-axis | Arm length | 200mm |
| | | Rotation range | ±130° |
| | Y-axis | Arm length | 200mm |
| | | Rotation range | ±147° |
| | Z-axis | Travelling distance | 150mm |
| | R-axis | Rotation range | ±360° |
| Max. Speed | | X-axis | 600°/S |
| | | Y-axis | 600°/S |
| | | Combination of X&Y-axis | 6.1m/s |
| | | Z-axis | 1.3m/s |
| | | R-axis | 6000°/s |
| Standard cycle time | | | 0.6s |
| Position Repeatability | | X&Y-axis | ±0.025mm |
| | | Z-axis | ±0.01mm |
| | | R-axis | ±0.03° |
| Rated/Max. Payload | | | 1Kg/2kg |
| Inertia moment within permissable payload of R-axis(Rated/Max.) | | | 0.002 kg·m2 |
| | | | 0.005 kg·m2 |
| Signal cable for user | | | 0.15sq×26 |
| Tubing for user | | | Φ6×2 |
| Limiting position protection | | | Software position limitation<br>Mechanical position limitation(X&Y&Z-axis) |
| Weight | | | 16Kg |

### ADT-400X4H150-011 (Floor mounted Standard) (Unit: mm)

Working range and external dimension



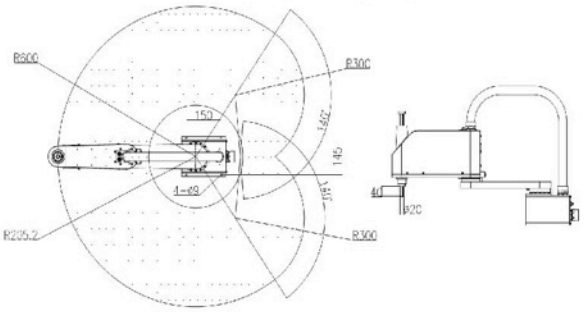
## ADT-600X4H300-051

### Product picture & Specifications


| | | | ADT-600X4H300-051 |
|---|---|---|---|
| Type | | | Horizontally multi-joint |
| Number of axis | | | 4 |
| Reach | | | 600mm |
| Axis specifications | X-axis | Arm length | 300mm |
| | | Rotation range | ±125° |
| | Y-axis | Arm length | 200mm |
| | | Rotation range | ±140° |
| | Z-axis | Travelling distance | 200mm |
| | R-axis | Rotation range | ±360° |
| Max. Speed | | X-axis | 375°/S |
| | | Y-axis | 600°/S |
| | | Combination of X&Y-axis | 7.1m/s |
| | | Z-axis | 1.1m/s |
| | | R-axis | 1500°/s |
| Standard cycle time | | | 0.5s |
| Position Repeatability | | X&Y-axis | ±0.03mm |
| | | Z-axis | ±0.015mm |
| | | R-axis | ±0.03° |
| Rated/Max. Payload | | | 3Kg/6kg |
| Inertia moment within permissable payload of R-axis(Rated/Max.) | | | 0.001 kg·m2 |
| | | | 0.004 kg·m2 |
| Signal cable for user | | | 0.15sq×26 |
| Tubing for user | | | Φ6×3 |
| Limiting position protection | | | Software position limitation<br>Mechanical position limitation(X&Y&Z-axis) |
| Weight | | | 40Kg |

### ADT-600X4H300-051 (Floor mounted Standard) (Unit: mm)

Working range and external dimension



| Model | | SD500 | SD700 | SA1400 | SA1500 | SA1800 | SA2010 |
|---|---|---|---|---|---|---|---|
| Number of axis | | 6 | 6 | 6 | 6 | 6 | 6 |
| Payload(kg) | | 1 | 1 | 6 | 6 | 8 | 8 |
| Max speed | J1 ( ° /s ) | 375 | 250 | 150 | 150 | 150 | 150 |
| | J2 ( ° /s ) | 375 | 185 | 150 | 150 | 150 | 120 |
| | J3 ( ° /s ) | 430 | 290 | 160 | 160 | 160 | 120 |
| | J4 ( ° /s ) | 460 | 460 | 360 | 360 | 360 | 360 |
| | J5 ( ° /s ) | 460 | 460 | 320 | 320 | 320 | 320 |
| | J6 ( ° /s ) | 600 | 600 | 360 | 360 | 360 | 360 |
| Max operating area | J1 ( ° ) | ±170 | ±170 | ±150 | ±150 | ±165 | ±165 |
| | J2 ( ° ) | ±115 | ±115 | +65~−180 | +65~−180 | +65~−180 | +65~−180 |
| | J3 ( ° ) | +40~−220 | +40~−220 | +160~−110 | +160~−110 | +170~−100 | +170~−100 |
| | J4 ( ° ) | ±185 | ±185 | ±170 | ±170 | ±185 | ±185 |
| | J5 ( ° ) | ±125 | ±125 | ±120 | ±120 | ±120 | ±120 |
| | J6 ( ° ) | ±360 | ±360 | ±360 | ±360 | ±360 | ±360 |
| Max working radius | | 500 | 700 | 1405 | 1505 | 1818 | 2010 |
| Weight | | 26 | 28 | 140 | 145 | 148 | 232 |
| Position repeatability | | ±0.015 | ±0.02 | ±0.05 | ±0.05 | ±0.05 | ±0.05 |
| Mounting condition | | floor, tilted, inverted | | | | | |
| Applications | | Welding, handling, palletizing, bending, cutting, polishing etc. | | | | | |
| Arm type | | Vertically multi-joint | | | | | |
| Control system | | SRC4 | | | | | |
| Mounting condition | Environment temperature | (0~45) ℃ | | | | | |
| | Relative humidity | 35%~85% Frost free | | | | | |
| | Vibration | below 0.5kg | | | | | |
| | Others | Robot mounting must be away from the disturbance of flammable, corrosive liquids and gas as well as electricity. | | | | | |

| SR20 | SR25 | SR50 | SR165 | SR210 | SP200 | SP275 |
|---|---|---|---|---|---|---|
| 6 | 6 | 6 | 6 | 6 | 4 | 4 |
| 20 | 25 | 50 | 165 | 210 | 200 | 275 |
| 150 | 150 | 120 | 110 | 95 | 120 | 80 |
| 120 | 120 | 100 | 110 | 85 | 120 | 80 |
| 120 | 120 | 100 | 110 | 95 | 120 | 80 |
| 360 | 300 | 180 | 175 | 125 | 300 | 200 |
| 300 | 300 | 180 | 150 | 125 | | |
| 450 | 360 | 200 | 240 | 190 | | |
| ±165 | ±165 | ±165 | ±165 | ±165 | ±180 | ±180 |
| +40~−155 | +40~−155 | +40~−150 | −5~−140 | −5~−140 | +75~−40 | +75~−40 |
| +165~−100 | +170~−70 | +165~−105 | +170~−60 | +170~−40 | +115~−20 | +115~−20 |
| ±360 | ±360 | ±360 | ±360 | ±360 | ±360 | ±360 |
| ±120 | ±120 | ±120 | ±125 | ±120 | | |
| ±360 | ±360 | ±360 | ±360 | ±360 | | |
| 1588 | 1790 | 2110 | 2586 | 2687 | 3039 | 3039 |
| 240 | 288 | 510 | 1250 | 1250 | 1815 | 1850 |
| ±0.05 | ±0.05 | ±0.25 | ±0.25 | ±0.25 | ±0.5 | ±0.5 |
| floor, tilted, inverted | | floor | | | | |
| Welding, handling, palletizing, bending, cutting, polishing etc. | | | | | | |
| Vertically multi-joint | | | | | | |
| SRC4 | | | | | | |
| (0~45) ℃ | | | | | | |
| 35%~85% Frost free | | | | | | |
| below 0.5kg | | | | | | |
| Robot mounting must be away from the disturbance of flammable, corrosive liquids and gas as well as electricity. | | | | | | |